Ismael Monge Rouchdi +34 689 007 389 | 01ismaelmon@gmail.com | Toulouse, France

LinkedIn | GitHub

Education

Master's degree in Robotic and Interactive Systems - University of Toulouse III, Toulouse Bachelor's Degree in Electronics, Electrical Energy, and Automation - University of Toulouse III, Toulouse

Personal projects

Continental Hackathon "HACK2MOVE"

Participated in the Continental Toulouse Hackathon, received recognition from the factory manager, André Goncalves, for our project idea, who confirmed the start of its development with his team a few days later.

Formula Student - Driverless Formula

- Selected to represent Toulouse in an international competition to develop a fully autonomous racing car, focusing on achieving full . vehicle autonomy at both low and high speeds, with real-time adaptation to weather conditions.
- Worked on the vehicle's autonomy, primarily focusing on the software aspects related to vehicle perception, including traffic cone position detection, sensor fusion modeling, and stereo depth estimation.

Head of the microcontrollers team at the Robotics club

Currently building up and programming a robotic industrial arm from scratch. It should be able at the end to pick objects of interest detected by a camera attached to it and move them as commanded within its range of motion.

Academic projects

Robot trajectory and speed planning (Engineering Consultancy Robotic Modeling on GitHub)	2024-2025
• Developed a kinematic model of an RRR robotic arm, calculating its linear, angular and joint velocities, a trajectory.	s well as planning its circular
• Implemented the 3D visualizations and movement animation to represent its position in real-time, allowin simulation of its performance.	ng an interactive and precise
• Ranked as Top1 project of the class.	
Autonomous Mobile Robot (<u>MobotSim</u> & <u>Mobot</u> on GitHub)	2023-2024
• Led the project by structuring the plan and managing internal communications for task distribution while point of contact with the client.	
• Ranked as the Top 1 voice commands recognition system by the jury, professionals from this particular domentation of the system of the sys	main.
 Designed a 4-wheel mobile robot capable of scanning a room, receiving and executing voice commands, r hitting walls, and detecting and differentiating obstacles. 	navigating the room without
Industrial automation (link)	2023-2024
• Completed automation of a model simulating an industrial chain for picking up and placing objects in sc simulation, state graphs and C language.	baking tanks using the model's
Research work on wireless power transfer, WPT (<u>link</u>)	2022-2023
• Studied wireless power transfer at short and long distances and its potential future applications.	
• Investigated the structure of a rectenna and the behavior of the rectifier and diode.	
C Program for Electronic Circuits (link)	2022-2023

Implemented a process using a file describing the components used in a circuit, able to calculate the impedance of these, as well as the current in each loop and the gain in dB to ultimately plot a Bode diagram.

Skills

Languages: English (Proficient), French (Native), Spanish (Native), German (Beginner)

Robotics: Robotic kinematics & trajectory planning, Control of discrete and sequential Systems, Computer vision & processing (OpenCV), Speech processing & recognition, Machine, deep & reinforcement learning (TensorFlow, PyTorch) Programming: C, Python, C++, Multitasking programming, Java, Arduino, VHDL, Val3, ST Software: MATLAB, ROS/ROS2, UNIX, Git, Stäubli Robotics Suite, Octave, LTSpice Hardware: STM32F4, NVIDIA Jetson Xavier 16GB, LiDAR, Stereo camera Soft skills: Curiosity, creative problem solving, clear communication, efficient organization, teamwork

Professional Experience

Ski Instructor

- Taught skiing lessons to individuals of all levels.
- Developed clear communication skills to effectively instruct students with different attention spans.
- Strengthened my leadership by managing group lessons with students of diverse personalities.
- Enhanced problem-solving by addressing challenges and providing support based on each student's mentality and skills.



June 2023

2024-2025

2024-2025

2024-2025

2018-Present